

# Mechanism Design for Social Good

Provision and Targeting for Vulnerable Populations

EC 2020 Tutorial, June 25 and 26

**Session #1b**

Self-targeting: theoretical models

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# Possible Errors in Targeting

Type II errors (award errors): ineligible individuals getting benefits

ineligible individuals getting benefits and being accepted

Type I error: eligible individuals not getting benefits

Type Ib errors (rejection errors): eligible individuals applying for benefits and being rejected.

AND

Type Ia errors (incomplete take-up): eligible individuals not applying for benefits.

# Theoretical groundwork: outline

- Ordeal targeting: sacrificing productive efficiency for targeting efficiency
- How is ordeal targeting supposed to work?
  
- Theoretically, does increasing ordeals improve targeting efficiency?
  - Depends on cost shocks
  - Depends on technology to overcome ordeal
  - Depends on curvature of utility function
- Some empirical evidence
  
- It looks like an ordeal, but it is productive! Productive complexity.

# What is ordeal targeting?

- Types (wage rate, consumption):  $a_i$   $i \in \{L, H\}$  (poor, not poor)
- Gov goal: want to give benefit  $B$  to  $a_L$  but can't observe  $a_i$   
(In this talk we will ignore paying for  $B$  by taxing  $a_H$  (Nichols & Zeckhauser, 1982))
- Program: Give  $B$  to applicants with probability  $P$ .  $P(a_L) > P(a_H)$
- Problem:  $a_H$  still apply. (Type II error)
- Solution: Set application cost  $C(a_i, s)$   
where  $s$  is ordeal level e.g standing in line  $s$  hours cost  $s \cdot \text{wage rate}$
- Result:  $a_H$  will not apply, thus improving targeting efficiency

# Examples

- Unemployment schemes require individuals to report to the unemployment office weekly during working hours, which is challenging for the employed
- Oportunidades in Mexico: appear in person to apply and recertify periodically, attending monthly health lectures
- Manual labor requirements to receive aid in welfare programs:
  - Works Progress Administration (WPA) in US Great Depression
  - National Rural Employment Guarantee Act (NREGA) right-to-work in India

# What's the problem with ordeal targeting?

$a_L$  that applies pay ordeal cost  $C(s, a_L)$

- Dead Weight Loss (DWL) – a waste if not balanced by better targeting
- Cost born by the poor
- May discourage application among the poorest (Type 1a error)

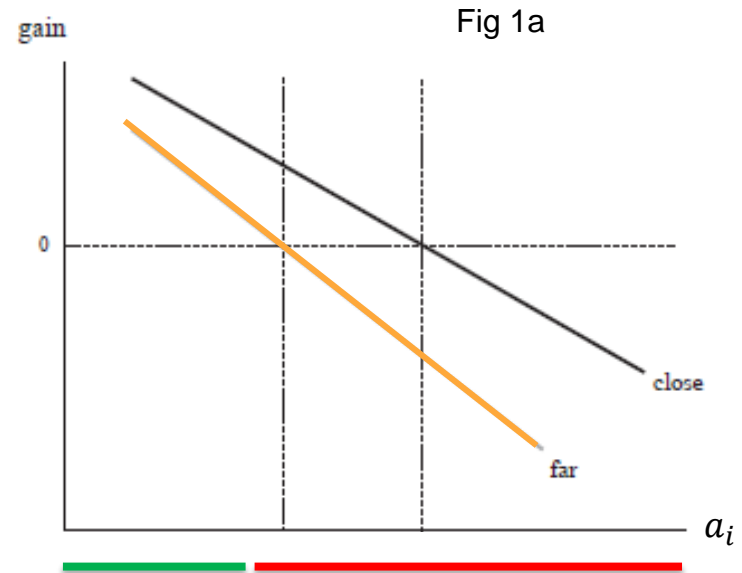
# Baseline model

- $\frac{\partial P(\cdot)}{\partial a_i} < 0, \frac{\partial C(L, a_i)}{\partial a_i} > 0$

- Apply:  $U(a_i - C(s, a_i)) + P(a_i)\delta U(a_i + B)) + (1 - P(a_i))\delta U(a_i)$
- Not apply:  $U(a_i) + \delta U(a_i)$

- Simplification:  $U(x) = x$   $C(s, a_i) = sa_i$
- $G(\text{ain}): -sa_i + P(a_i)\delta B$
- Apply if  $G > 0$

- $\frac{\partial G}{\partial a_i} < 0, \frac{\partial G}{\partial s} < 0,$
- Increasing  $s$  decreases threshold type



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- Apply if  $G > 0$

- So  $s$  improves targeting efficiency when:

$$\frac{\Pr(\text{apply}|a_L; s)}{\Pr(\text{apply}|a_H; s)}$$

is increasing in  $s$

Fig 1b: No errors  
Not poor hurt more w/ increasing L





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# Extension: Cost shocks

- When applying, people experience  $\epsilon$  shocks.
  - $\epsilon > 0 \Rightarrow$  more likely to apply (have child care),  $\epsilon < 0$  less likely (sick child).
  - Distributed w/ cdf  $F(\cdot)$ , mean 0 variance  $\sigma^2$ .
- Apply:  $U(a_i - C(s, a_i)) + P(a_i)\delta U(a_i + B) + (1 - P(a_i))\delta U(a_i) + \epsilon$
- Not apply:  $U(a_i) + \delta U(a_i)$
- Now apply if  $sa_i + P(a_i)\delta B + \epsilon > 0$  or  $G(a_i, s) + \epsilon > 0$
- $\Pr(\text{apply}|a_i, s) = 1 - F(-G(a_i, s))$
- So  $s$  improves targeting efficiency when:
   
 $\frac{1 - F(-G(a_L, s))}{1 - F(-G(a_H, s))}$  is increasing in  $s$  .

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  - $\epsilon > 0 \Rightarrow$  more likely to apply (have child care),  $\epsilon < 0$  less likely (sick child).
  - Distributed w/ cdf  $F(\cdot)$  mean 0 variance  $\sigma^2$
  
- $\frac{1-F(-G(s,a_L))}{1-F(-G(s,a_H))}$  is increasing in  $s$  when
  - distribution of shocks have the monotone hazard property
  
- Meaning hazard rate  $\frac{f(-G(s,a_i))}{1-F(-G(s,a_i))}$  is increasing in  $a_i$ 
  - e.g. uniform, normal, logistic distribution
  - but not log logistic and other “thick-tailed” distributions

# Effect of increasing ordeal w/ and w/out cost shocks

Fig 2a: Log logistic errors  
 Poor hurt more w/ increasing L

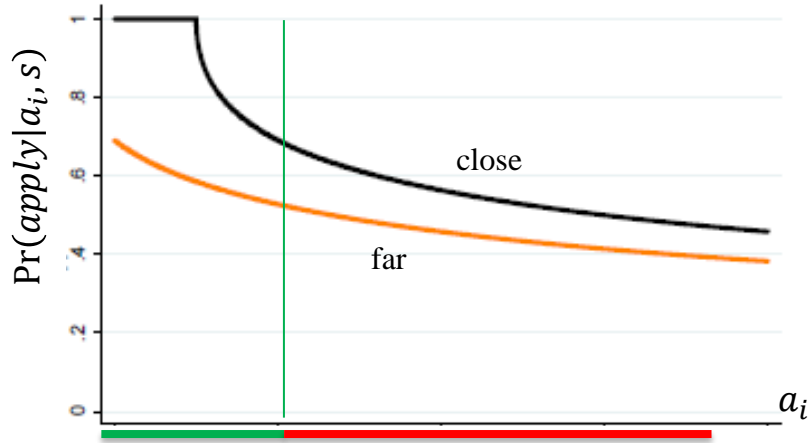


Fig 1b: No errors  
 Not poor hurt more w/ increasing L



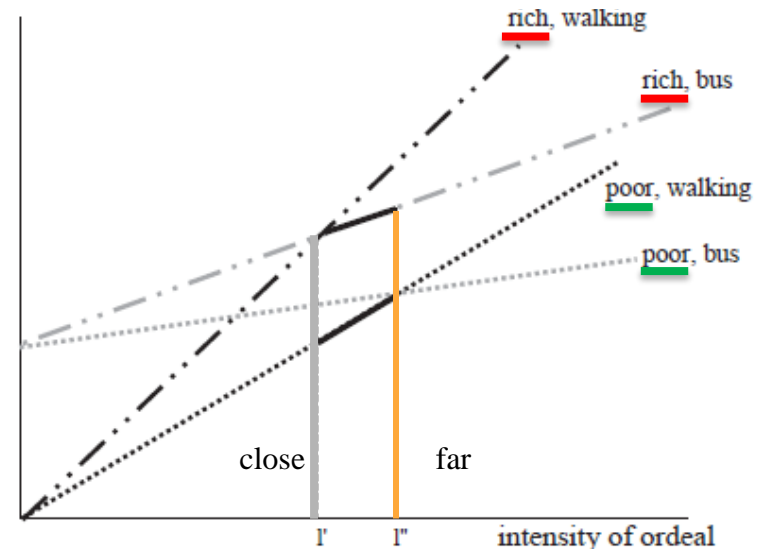
# Extension: Technology to overcome ordeal

- Previously:  $C(s, a_i) = sa_i$  (standing in line  $s$  hours \* wage rate)
- Now: suppose you have to travel  $s$  km to apply for  $B$
- You can walk or bus:  $l > k$

Walking:  $lsa_i$

Bussing:  $v + ksa_i$

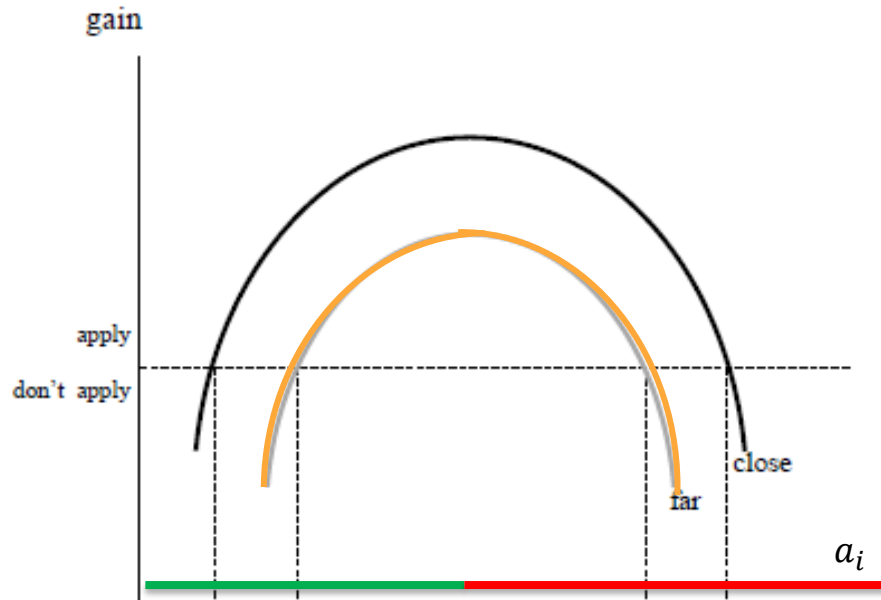
- Increasing ordeal:
  - From 0 to *close* improves targeting
  - From *close* to *far* harms targeting (marginal cost for the poor is increasing more than for the rich.)



# Extension: Concave utility

$$U(x) = \ln(x)$$

$$G = \ln(a_i - C(s, a_i)) + P(a_i)\delta \ln(a_i + B) + (1 - P(a_i))\delta \ln(a_i) - \ln(a_i) + \delta \ln(a_i)$$



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# PKH self-targeting experiment

2010 Collect  
consumption  
data LNPCE

2011 PMT  
and self  
targeting

Give B  
(4-13% of  
income),

substantial under  
reporting of assets in  
the initial interview

Interviewer  
come to house

Go to office to  
be interviewed

	Total households	% interviewed (applied)	% received benefits   interview	% (from total) that receive benefits
No ordeal	1998	35.3%	12.18%	4.3%
Ordeal	2000	37.7%	9.7%	3.7%



<b>Far</b> , Self (500)	Close, Self
<b>Far</b> , <b>+Spouse</b>	Close, <b>+Spouse</b>



# Ordeal: who shows up ?

- Regress  $LNPCE_i = \alpha_1 + PMT_i \beta + \varepsilon_i$
- Regress  $ShowUp_i$  against  $PMT_i \beta$  and  $\varepsilon_i$

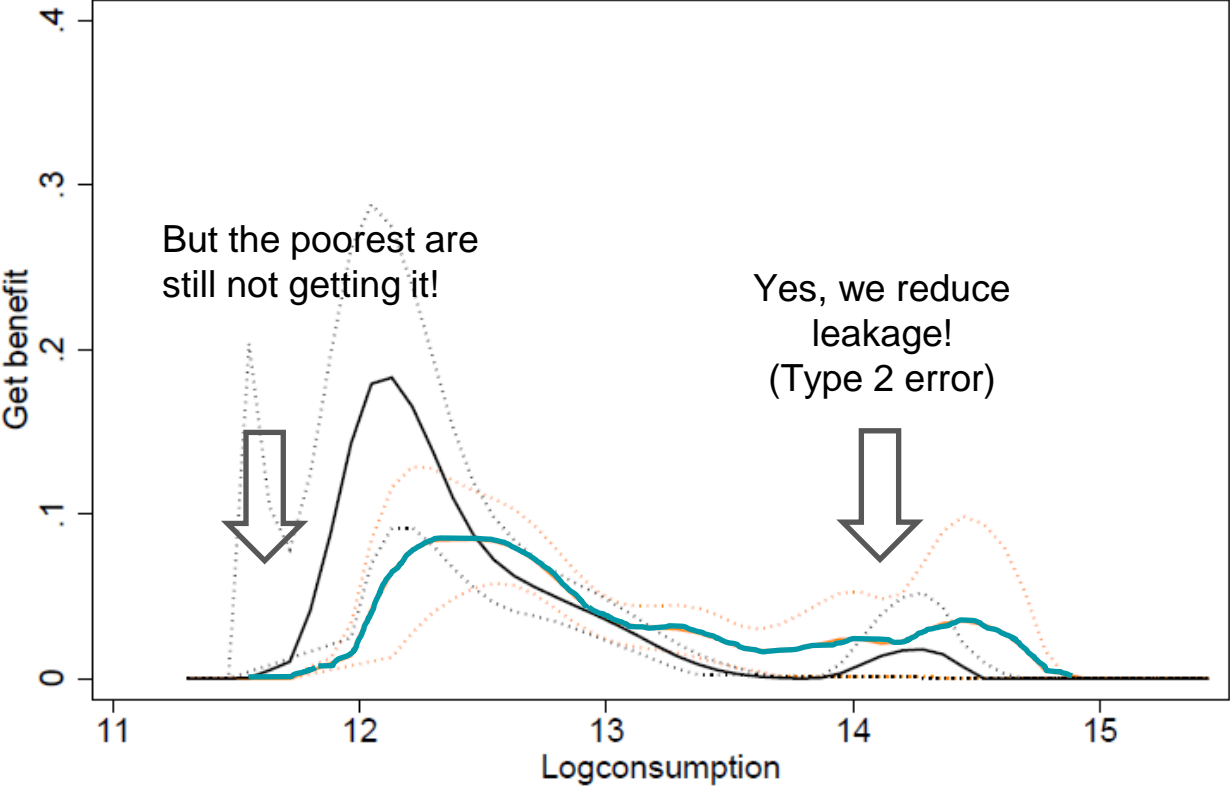
Selection from ordeal  
consistent with PMT

...and is likely to  
improve upon it



	$ShowUp_i$
	All (1)
Observable consumption ( $X_i' \beta$ )	-2.217*** (0.201)
Unobservable consumption ( $\varepsilon_i$ )	-0.907*** (0.136)
Stratum fixed effects	No
Observations	2,000
Mean of dependent variable	0.377

# Ordeal improves targeting



No ordeal    Automatic Enrollment    Self-Targeting    Ordeal

# Increasing ordeal: +spouse

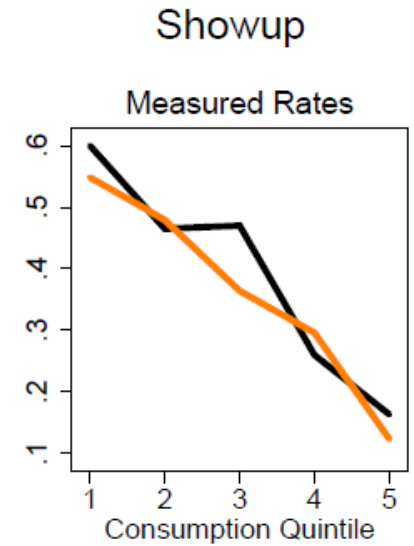
TABLE 8. Experimental Results: Probability of Showing up as a Function

	No stratum fixed effects		
	(1)	(2)	(3)
Both spouse subtreatment	0.196 (0.146)	4.303 (2.840)	0.461* (0.237)
Log consumption		-1.324*** (0.145)	
Both spouse subtreatment * Log consumption		-0.318 (0.217)	

# Increasing ordeal: +distance

TABLE 7. Experimental Results: Probability of Showing up as a Function of Distance

	No stratum fixed effects		
	(1)	(2)	(3)
Close subtreatment	0.205 (0.146)	1.345 (2.841)	0.195 (0.238)
Log consumption		-1.434*** (0.143)	
Close subtreatment* Log consumption		-0.093 (0.217)	



Why? Which of the three theoretical possibilities explains it?

# Umm... none.

- cost shocks:
  - logistic error fits best, and it satisfy the monotone hazard property
- technology to overcome ordeal:
  - May be possible, but when simulate data constraining everyone to the same transport technology, no difference.
- curvature of utility function:
  - linear utility fits best
- So?? Why doesn't increasing ordeal improve targeting
  - Spouse: 28% request exemptions
  - Distance: 1.67 km
  - What would have worked is 6 hours wait (but that would be bad)
- This is where theory meets the limits of policy implementation.

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**TABLE 1. SOCIAL PROGRAMS IN THE UNITED STATES**

PROGRAM	TAKE UP <sup>1</sup>	TARGETING <sup>2</sup>	COMPLEXITY <sup>2</sup>
Medicaid	73%	Medium	High
Medicare Part B <sup>3</sup>	96%	Low	Low
Supplemental Security Income Program (SSI)	60%	High	High
Social Security Disability Insurance (DI)	No estimate	High	High
The Earned Income Tax Credit (EITC)	80%-86%	Medium	High
Temporary Assistance for Needy Families (TANF) <sup>4</sup>	60%-90%	Medium	High
Housing Programs	below 50%	Medium	High
Food Stamps	69%	Medium	Medium
The Special Supplemental Nutrition Program for Women, Infants and Children (WIC)	67%, 73%, 38%	High	High
Child Care Subsidies	40%	Medium	High

Strictness of eligibility criteria  
Moffitt (2003), Currie (2004)

All transaction costs



# Incomplete takeup is an issue not just in the US

<b>Country</b>	<b>Name of programme</b>	<b>Targeting accuracy for poorest quintile</b>	<b>Under-coverage (percentage of poor not reached)</b>
Brazil	Bolsa Escola	1.98	73
Chile	PASIS (Pensiones Asistenciales de Ancianidad y de Invalidez) (old-age benefits)	2.67	84
Chile	Subsidio Única Familiar (SUF) (cash transfers)	3.32	73
Colombia	Subsidized Health Insurance Regime (SHIR) (health social assistance)	1.68	26
Mexico	Oportunidades	2.9	40

# Reducing random noise with program complexity

- As before, each individual has ability level  $a$ .
- $a$  can be only be observed by gov with noise level  $\sigma$  (language barriers, health):  $\epsilon/\sigma \sim 0,1$ , cdf  $P(\cdot)$ ,  $P(0) = 1/2$ . Individual knows own  $\sigma$  but not  $\epsilon$ .
- Difference with Alatas et al (2016):  $\epsilon$  is noise in signal of ability, not cost shock that is observed by individual when applying for benefits.
- Individual apply for benefits with screening intensity  $\alpha$  (# of interviews/forms) with increasing cost function  $f(\alpha)$  (transaction cost).
- Gov can reduce noise by increasing  $\alpha$ :  $a' = a + \frac{\epsilon}{\alpha}$

# Gov policy instruments:

As before assume 2 types  $a_i$   $i \in \{L, H\}$  (poor, not poor)

Government have a budget of  $R$  and seek to give out a benefit  $B \leq \bar{B}$  to as many  $a_L$  as possible using 3 policy levers:

- $\alpha$  :screening intensity/ transaction costs  $\alpha \uparrow \quad f(\alpha) \uparrow \frac{\epsilon}{\alpha} \downarrow$
- $\bar{a}$  :strictness of eligibility criteria/ threshold  $a' = a + \frac{\epsilon}{\alpha} < \bar{a}$  receives  $B$
- $B$  :program benefit  $B \uparrow \quad u(a_i + B - f(\alpha)) \uparrow$

$$\max_{\alpha, \bar{a}, B} N_L(\alpha, \bar{a}, B)$$

s.t

$$[N_L(\alpha, \bar{a}, B) + N_H(\alpha, \bar{a}, B)] B \leq R$$

# Effect of policy instruments on $i$ 's decision to apply

- Get benefit when  $a_i + \frac{\epsilon}{\alpha} < \bar{a}$  so  $\Pr(B|apply) = \Pr(\epsilon < \frac{\alpha(\bar{a}-a_i)}{\sigma_i}) = P(\frac{\alpha(\bar{a}-a_i)}{\sigma_i})$
- Apply when

$$P(\frac{\alpha(\bar{a}-a_i)}{\sigma_i}) u(a_i + B - f(\alpha)) + (1 - P(\frac{\alpha(\bar{a}-a_i)}{\sigma_i})) u(a_i - f(\alpha)) > u(a_i)$$

- Rearranging, we see that policy  $\alpha, B$  sets a threshold probability:

$$\tilde{P}(\alpha, B) \equiv \frac{u(a_i) - u(a_i - f(\alpha))}{u(a_i + B - f(\alpha)) - u(a_i - f(\alpha))}$$

- Individual  $a_i, \sigma_i$  will only apply if

$$P(\frac{\alpha(\bar{a}-a_i)}{\sigma_i}) > \tilde{P}(\alpha, B)$$

## $\bar{a}$ (strictness of eligibility criteria)

Individual  $a_i, \sigma_i$  will only apply if

$$P\left(\frac{\alpha(\bar{a}-a_i)}{\sigma_i}\right) > \tilde{P}(\alpha, B)$$

- STRICT:  $\bar{a} < a_L < a_H$  (w/ no noise no one should get it).  
Pr (apply) decrease in precision.
- $a_L < \bar{a} < a_H$  (w/ no noise  $a_L$  should get it).  
Pr (apply) increase in precision for  $a_L$  and decrease in precision for  $a_H$  .
- LENIENT:  $a_L < a_H < \bar{a}$  (w/ no noise everyone should get it).  
Pr (apply) increase in precision.



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